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**OKLAHOMA STATE UNIVERSITY**  
**Department of Mathematics**

**Calculus III (MATH 2163)**  
Instructor: Mathias Schulze

**FINAL EXAM**  
**December 11/15, 2006**

**Duration: 110 minutes**

**No aids allowed.**

This examination paper consists of **5** pages and **8** questions. Please bring any discrepancy to the attention of an invigilator. The number in brackets at the start of each question is the number of points the question is worth.

Answer **7 of 8** questions.

**To obtain credit, you must explicitly state your result and give arguments to support your answer.**

For graders' use:

	Score
1 (10)	
2 (10)	
3 (10)	
4 (10)	
5 (10)	
6 (10)	
7 (10)	
8 (10)	
<b>Total (80)</b>	

1. [10] Find the linearization of the function  $f(x, y) = \sqrt{20 - x^2 - 7y^2}$  at  $(2, 1)$  and write it in the form  $L(x, y) = a + bx + cy$ . Use your result to approximate  $f(1.95, 1.08)$ . Write down the differential of  $f$  explicitly.

**Solution:** In the review session I recommended to review linearization and differential at home. The first part was even a homework problem for Lecture 10.

First compute the partial derivatives,

$$f_x = -\frac{x}{\sqrt{20 - x^2 - 7y^2}}, \quad f_y = -\frac{7y}{\sqrt{20 - x^2 - 7y^2}},$$

and evaluate at  $(2, 1)$ ,  $f(2, 1) = 3$ ,  $f_x(2, 1) = -\frac{2}{3}$ ,  $f_y(2, 1) = -\frac{7}{3}$ . Then the linearization of  $f$  at  $(2, 1)$  is given by the formula

$$\begin{aligned} L(x, y) &= f(2, 1) + f_x(2, 1)(x - 2) + f_y(2, 1)(y - 1) \\ &= 3 - \frac{2}{3}(x - 2) - \frac{7}{3}(y - 1) = 3 + \frac{4}{3} + \frac{7}{3} - \frac{2}{3}x - \frac{7}{3}y = \frac{20}{3} - \frac{2}{3}x - \frac{7}{3}y. \end{aligned}$$

The linear approximation of  $f$  at  $(1.95, 1.08)$  is

$$f(1.95, 1.08) \approx L\left(2 - \frac{5}{100}, 1 + \frac{8}{100}\right) = 3 + \frac{2 \cdot 5}{3 \cdot 100} - \frac{7 \cdot 8}{3 \cdot 100} = \frac{427}{150} \approx 2.847.$$

The total differential of  $f$  is

$$df = f_x dx + f_y dy = -\frac{x dx + 7y dy}{\sqrt{20 - x^2 - 7y^2}}.$$

2. [10] Compute the gradient of  $f(x, y) = \frac{y^2}{x}$ . Determine the maximal and minimal rates of change of  $f$  at  $(2, 4)$  and unit vectors in the directions in which these rates of change occur. Find a unit vector in a direction in which  $f$  has zero rate of change at  $(2, 4)$ .

**Solution:** In the review session I recommended to review gradient, directional derivative, and rate of change at home.

The gradient equals

$$\vec{\nabla} f(x, y) = \left\langle -\frac{y^2}{x^2}, 2\frac{y}{x} \right\rangle.$$

The maximal and minimal/minimal rate of change of  $f$  at  $(2, 4)$  equals  $\pm|\vec{\nabla} f(2, 4)| = \pm|\langle -4, 4 \rangle| = \pm 4\sqrt{2}$  and occurs in direction of

$$\pm \frac{\vec{\nabla} f(2, 4)}{|\vec{\nabla} f(2, 4)|} = \pm \frac{\langle -4, 4 \rangle}{4\sqrt{2}} = \left\langle \mp \frac{1}{\sqrt{2}}, \pm \frac{1}{\sqrt{2}} \right\rangle.$$

Orthogonally to these directions the rate of change of  $f$  at  $(2, 4)$  is zero. The corresponding unit vectors are simply  $\pm \left\langle \frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}} \right\rangle$ .

3. [10] Use Lagrange multipliers to find the maximal and minimal values of the function  $f(x, y) = x^2y^2$  subject to the constraint  $x^2 + y^2 = 1$ . (Hint: There are 8 critical points.)

**Solution:** This is essentially a simplified version of a problem discussed in the review session and of a homework problem for Lecture 19.

The gradients of  $f$  and  $g$  are

$$\vec{\nabla}f = 2\langle xy^2, x^2y \rangle, \quad \vec{\nabla}g = 2\langle x, y \rangle.$$

By the method of Lagrange multipliers, we have to solve the system

$$xy^2 = \lambda x, \quad x^2y = \lambda y, \quad x^2 + y^2 = 1.$$

By the last equation and symmetry we may assume that  $x \neq 0$ . Then the first equation gives  $\lambda = y^2$  and substituting into the second yields  $(x^2 - y^2)y = 0$ . So either  $y = 0$ , and hence  $x = \pm 1$  by the third equation, or  $0 = x^2 - y^2 = (x-y)(x+y)$ . In this latter case  $x = \pm y$  and the third equality gives  $|x| = |y| = \frac{1}{\sqrt{2}}$ . Reconsidering or symmetry argument, we have found 8 points:  $(\pm 1, 0)$ ,  $(0, \pm 1)$ ,  $(\pm \frac{1}{\sqrt{2}}, \pm \frac{1}{\sqrt{2}})$ ,  $(\pm \frac{1}{\sqrt{2}}, \mp \frac{1}{\sqrt{2}})$ . The function  $f$  is zero at the former 4 points and equals  $\frac{1}{4}$  at the latter 4 points. So 0 is the only minimal value and  $\frac{1}{4}$  is the only maximal value of  $f$  subject to the given constraint.

4. [10] Use spherical coordinates to find the volume of the solid that lies above the cone  $z = \sqrt{x^2 + y^2}$  and below the sphere  $x^2 + y^2 + z^2 = z$ .

**Solution:** This is Example 4 in Section 16.8 and has been discussed in class. In the review session I recommended to review volume computations in spherical coordinates at home.

5. [10] Integrate the vector field

$$\vec{F}(x, y) = \left\langle y - \frac{x}{\sqrt{x^2 + y^2}^3}, -x - \frac{y}{\sqrt{x^2 + y^2}^3} \right\rangle$$

along a clockwise oriented unit circle  $C$  centered at the origin. (Hint: Write  $\vec{F}$  as a sum of two vector fields.) Explain why  $\vec{F}$  is not conservative.

**Solution:** All ideas to solve this problem have been discussed in the review session.

The vector field decomposes as  $\vec{F} = \vec{G} + \vec{H}$  where  $\vec{G}(x, y) = \langle y, -x \rangle$  and

$$\vec{H}(x, y) = \left\langle -\frac{x}{\sqrt{x^2 + y^2}^3}, -\frac{y}{\sqrt{x^2 + y^2}^3} \right\rangle.$$

Up to constants,  $\vec{H}$  is just the gravitational/electric force known from the lecture. Hence  $\vec{H} = \vec{\nabla}h$  is conservative where, again up to constants,  $h(x, y) = \frac{1}{\sqrt{x^2 + y^2}}$  is the gravitational/electric potential. By the fundamental theorem of line integrals  $\int_C \vec{H} \cdot d\vec{r} = 0$  and so

$$\int_C \vec{F} \cdot d\vec{r} = \int_C \vec{G} \cdot d\vec{r}.$$

A clockwise parametrization of  $C$  is given by  $\vec{r}(t) = \langle \cos t, -\sin t \rangle$  where  $0 \leq t \leq 2\pi$  and hence

$$\begin{aligned} \int_C \vec{G} \cdot d\vec{r} &= \int_0^{2\pi} \vec{G}(\vec{r}(t)) \cdot \vec{r}'(t) dt \\ &= \int_0^{2\pi} \langle -\sin t, -\cos t \rangle \cdot \langle -\sin t, -\cos t \rangle dt = \int_0^{2\pi} dt = 2\pi. \end{aligned}$$

In particular, this result tells us that  $\vec{F}$  can not be conservative because integrals of conservative vector fields along closed curves are always zero.

6. [10] Evaluate the line integral  $\int_C z dx + x dy + y dz$  where  $C$  is the curve parametrized by  $x(t) = t, y(t) = t^2, z(t) = t^3$  for  $0 \leq t \leq 1$ .

**Solution:** This is equivalent to a homework problem for Lecture 41. Moreover, line integral w.r.t. coordinates have been discussed in the review session.

One computes

$$\begin{aligned} \int_C z dx + x dy + y dz &= \int_0^1 z(t)x'(t) + x(t)y'(t) + y(t)z'(t) dt \\ &= \int_0^1 t^3 \cdot 1 + t \cdot 2t + t^2 \cdot 3t^2 dt \\ &= \frac{1}{4} + \frac{2}{3} + \frac{3}{5} = \frac{15 + 40 + 36}{60} = \frac{91}{60}. \end{aligned}$$

7. [10] Compute the mass center of the circular cone  $C$  with constant density  $\rho$  defined by the inequalities  $0 \leq z \leq 1 - r$ .

**Solution:** A slightly modified version of this problem has been discussed in the review session.

By symmetry reasons the  $x$ - and  $y$ -coordinates of the mass center equal 0. Its  $z$ -coordinate is computed by the integral

$$\bar{z} = \frac{\int_C z \rho dV}{\int_C \rho dV} = \frac{\int_C z dV}{\int_C dV}.$$

To compute each of these integrals we use polar coordinates. There are values of  $z$  such that  $0 \leq z \leq 1 - r$  exactly if  $r \leq 1$ . Therefore

$$\int_C dV = \int_0^{2\pi} \int_0^1 \int_0^{1-r} dz r dr d\theta = 2\pi \int_0^1 r - r^2 dr = 2\pi \left( \frac{1}{2} - \frac{1}{3} \right) = \frac{\pi}{3}$$

and similarly

$$\int_C z dV = \pi \int_0^1 (1-r)^2 r dr = \pi \int_0^1 r - 2r^2 + r^3 dr = \pi \left( \frac{1}{2} - \frac{2}{3} + \frac{1}{4} \right) = \frac{\pi}{12}.$$

Thus  $\bar{z} = \frac{1}{4}$  and the mass center is  $(0, 0, \frac{1}{4})$ .

8. [10] Determine whether or not the vector field  $\vec{F} = \langle 6x + 5y, 5x + 4y \rangle$  is conservative. If it is, find a potential for  $\vec{F}$ . How many potentials for  $\vec{F}$  are there?

**Solution:** This example is known from the review session.

Set  $P = 6x + 5y$  and  $Q = 5x + 4y$  such that  $\vec{F} = \langle P, Q \rangle$ . Then  $\frac{\partial P}{\partial y} = 5 = \frac{\partial Q}{\partial x}$  and hence  $\vec{F}$  is conservative by the criterion from the lecture.

To find  $f$  we have to solve  $\langle P, Q \rangle = \vec{F} = \vec{\nabla} f = \langle f_x, f_y \rangle$  and hence the system of linear partial differential equations

$$6x + 5y = f_x, \quad 5x + 4y = f_y.$$

Integrating the first equation gives  $3x^2 + 5xy + g = f$  for some function  $g = g(y)$ . Substituting into the second equation we find  $5x + g' = f_y = 5x + 4y$  and then  $g = 2y^2 + c$  for any constant  $c$ .

By computing the gradient, we easily verify that  $f = 3x^2 + 5xy + 2y^2 + c$  is really a potential for  $\vec{F}$  for any constant  $c$ . In particular, there is an infinite number of such potentials, a different one for each real number  $c$ .

**End of examination**

**Total pages: 5**

**Total marks: 80**